

Statistical models of visual neurons

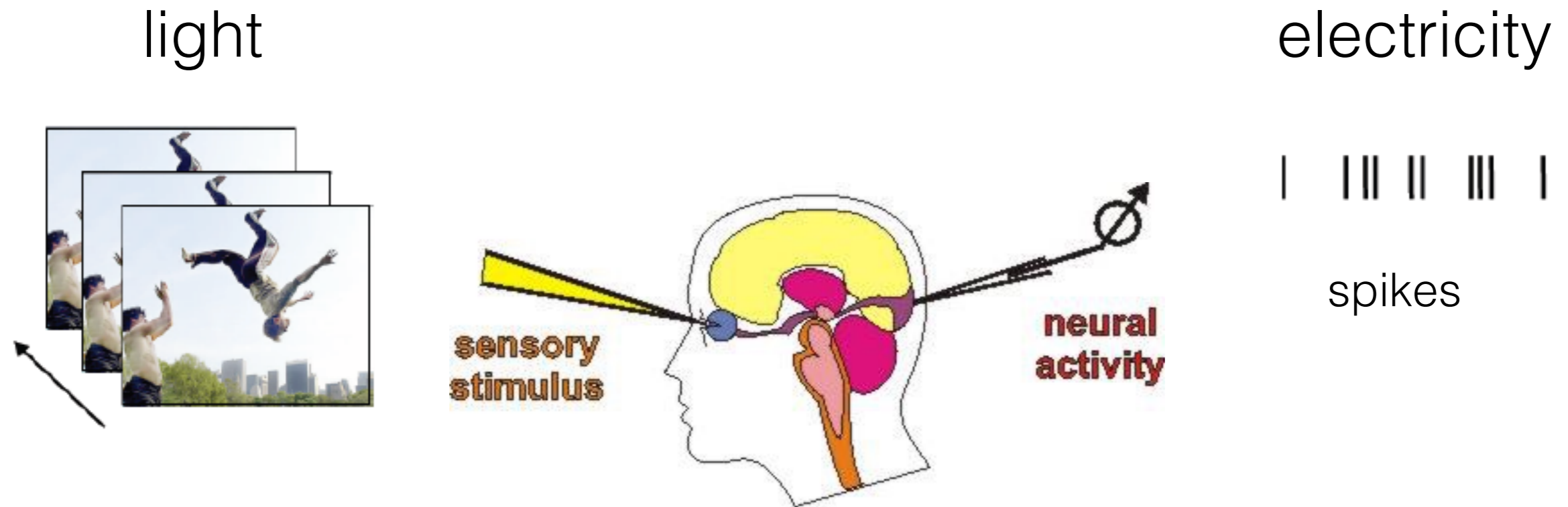
Update Presentation

Anna Sotnikova

Applied Mathematics and Statistics, and Scientific Computation
program

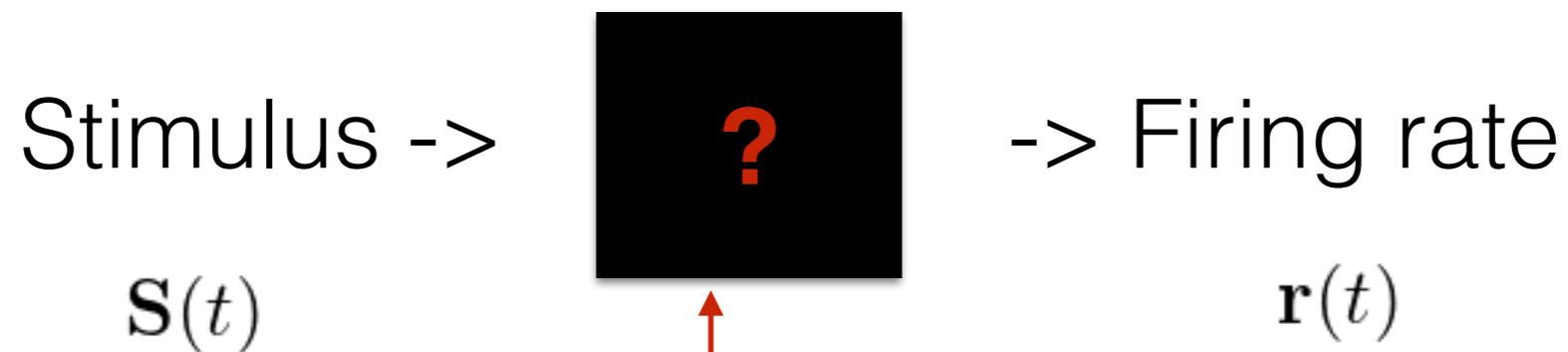
Advisor: Dr. Daniel A. Butts
Department of Biology

Visual system of a neuron



The goal of this field is to identify relationship between the visual stimuli and the resulting neural responses

Statistical modeling of neuron's response



$$Prob(n(t)) = \frac{r(t)^{n(t)}}{n(t)!} \exp(-r(t))$$

$n(t)$ - number of spikes at moment t

What is the simplest model which describes the computation being performed by the neuron?

Previous semester models

Linear-Nonlinear-Poisson model

- Moment-based statistical models for linear filter \mathbf{k} estimation:
 1. First order moment-based model - Spike Triggered Average (STA)
 2. Second order moment-based model - Spike Triggered Covariance (STC)

This semester models

Maximum Likelihood estimators:

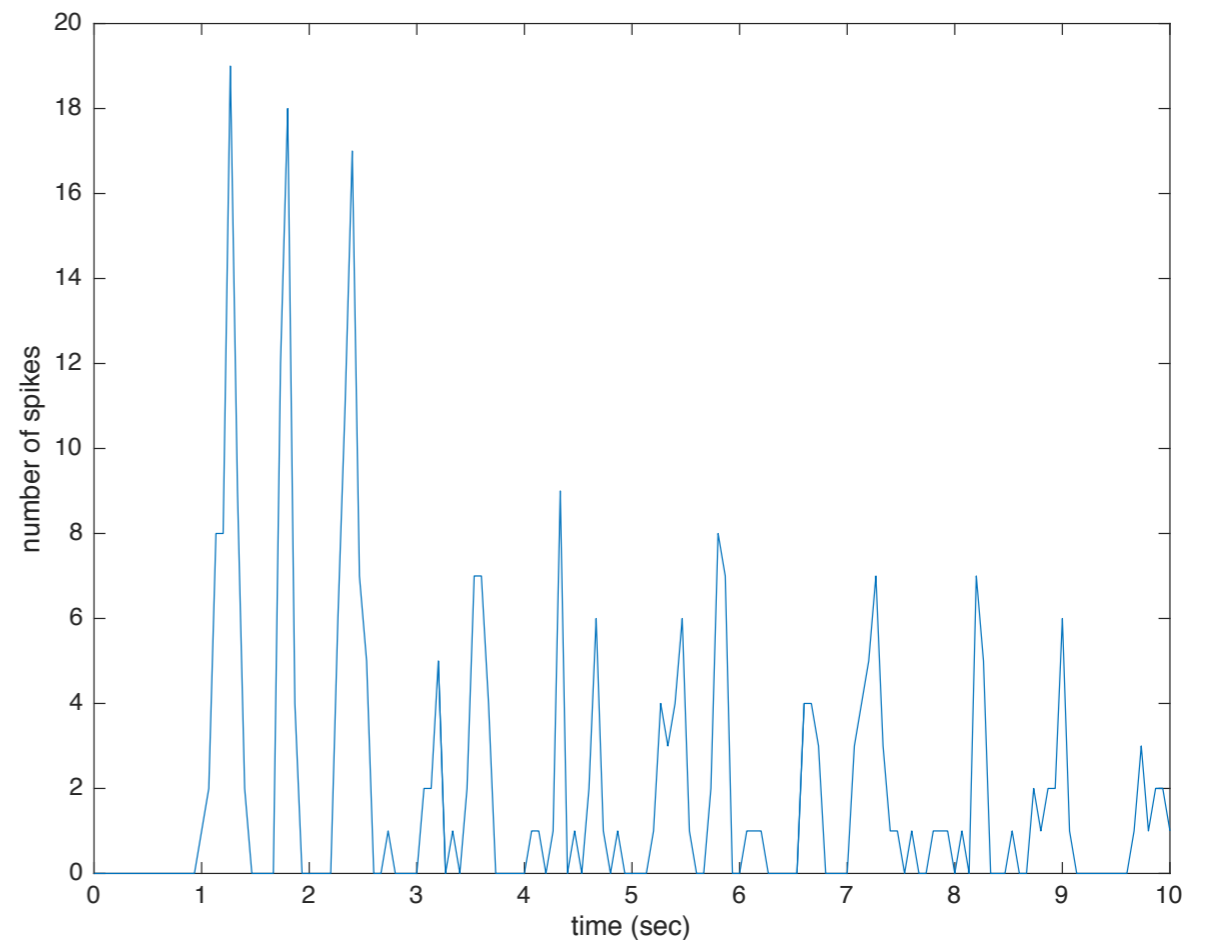
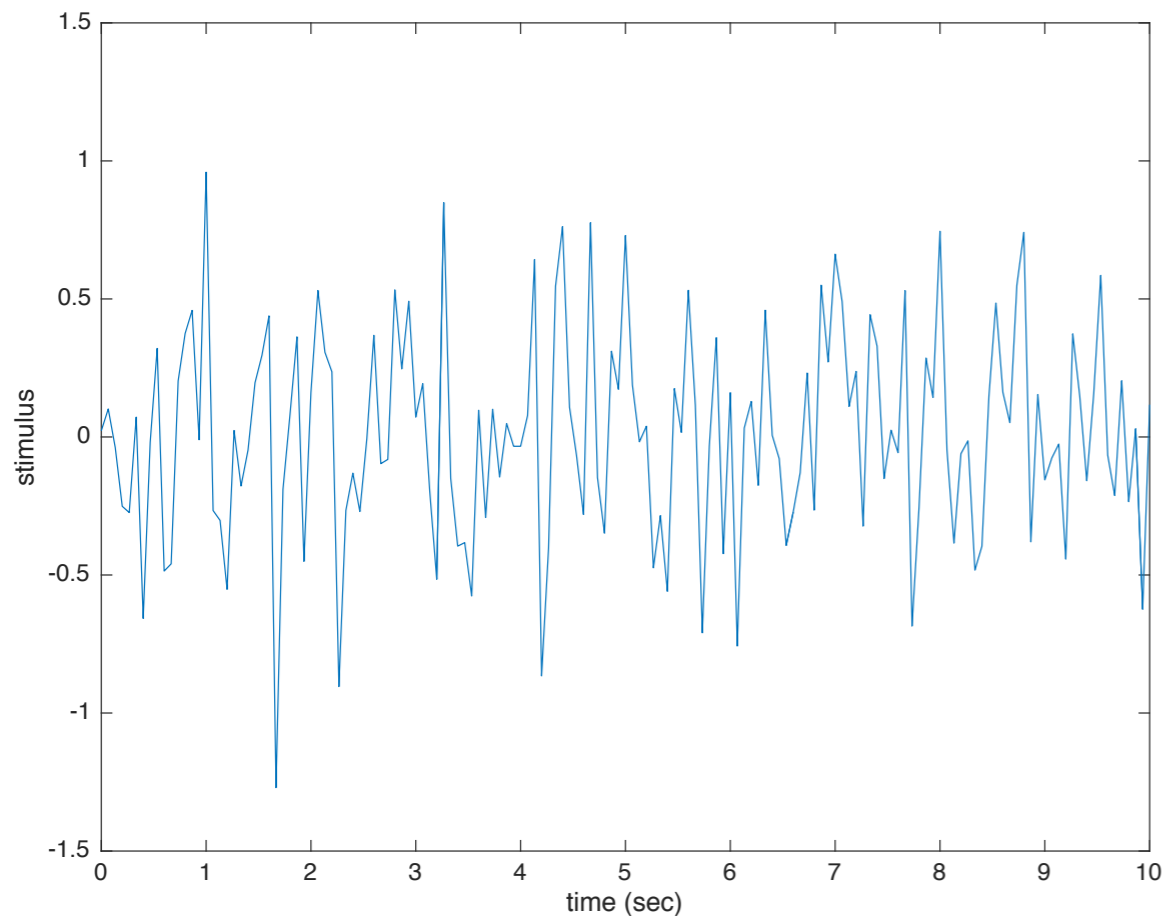
- Generalized Linear Model (GLM)
- Generalized Quadratic Model (GQM)
- Nonlinear Input Model (NIM)

Data sets description

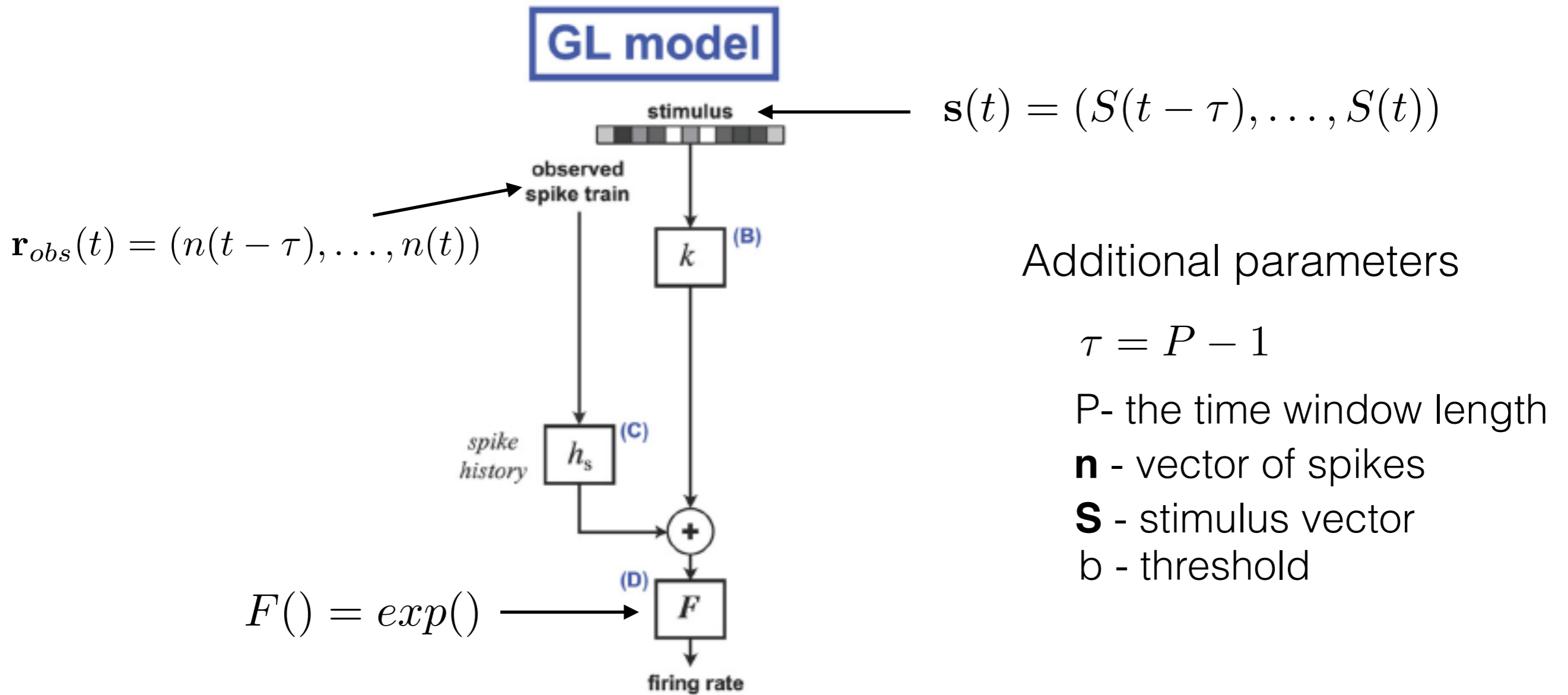
- Real data set - Lateral Geniculate Nucleus data (LGN)
- Synthetic data set - Retinal Ganglion Cells (RGC)

Both data sets contain :

1. Stimulus vector (\mathbf{s} , which depends on time)
2. Spikes vector (\mathbf{n} , which depends on time)
3. Time interval of the stimulus update (dt, time step)



Generalized Linear Model: Idea



$$r(t) = F(\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b)$$

GOAL: find optimal **k, h** and **b**

Generalized Linear Model (GLM): Plan

$$r(t) = F(\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b)$$

1. GLM: find LogLikelihood $LL[\mathbf{k}, \mathbf{h}, b] \rightarrow \max$
2. Validate the code using simulated data
 - a. without h and b terms
 - b. with h and b terms
3. Validate part of the model(without h and b terms) comparing with STA filter for RGC data set
4. Find optimal k and h filters for LGN data set

Maximum Likelihood estimation

$$P(N|\Theta) = \prod_t \frac{(r(t))^{n(t)}}{n(t)!} \exp(-r(t)) \quad \leftarrow \text{Poisson distribution}$$

$$N = \{n(t)\} \quad \Theta = \{r(t)\}$$

$$LL(\Theta) = \log(P(N|\Theta)) = \sum_t n(t) \log(r(t)) - \sum_t r(t)$$

$$r(t) = F(\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b) \quad \Theta = \{\mathbf{k}, \mathbf{h}, b\} \quad F() = \exp()$$

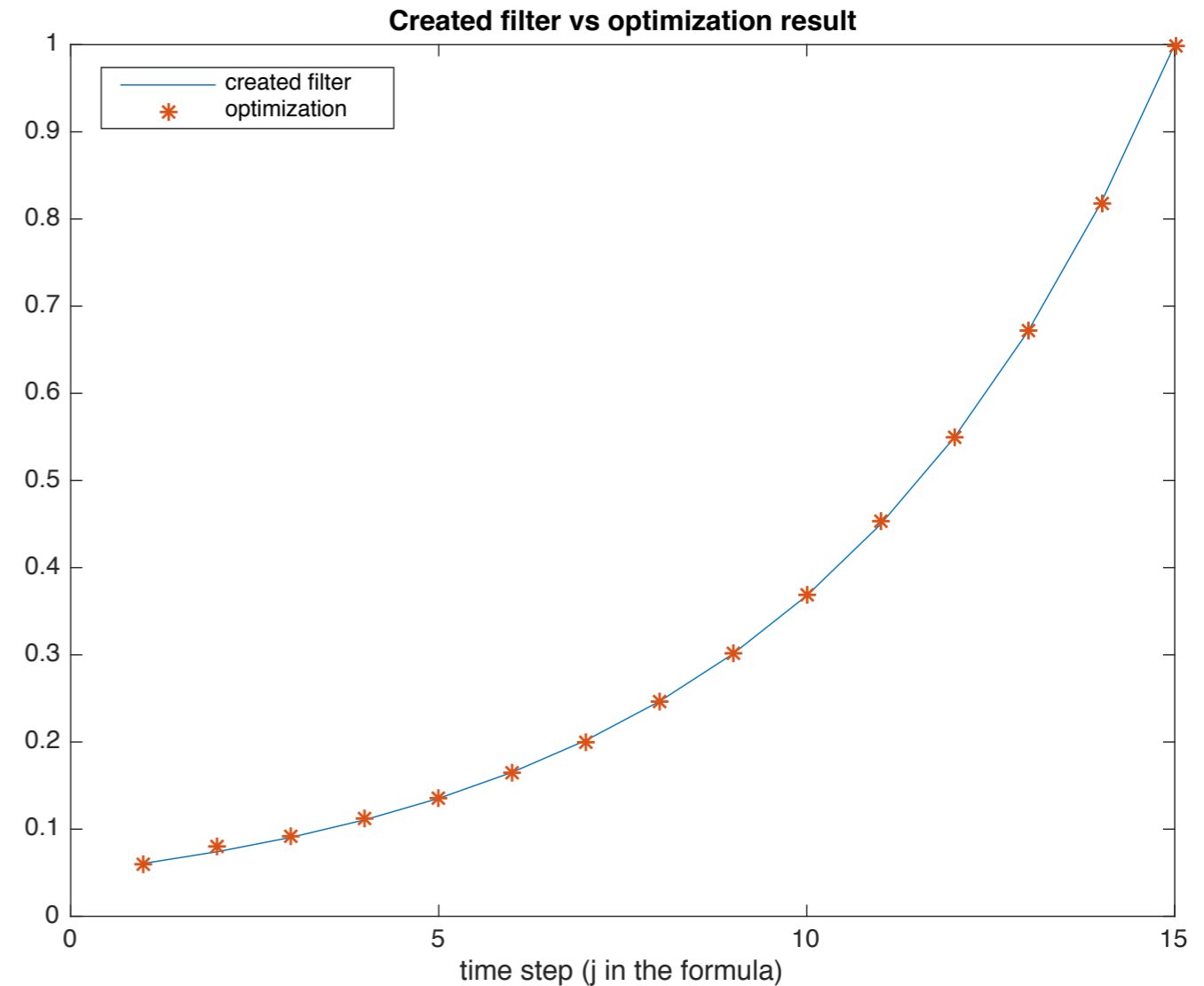
Solve log-likelihood using
gradient ascent method

$$LL(\Theta) = \sum_t n(t) (\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b) - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b)$$

GLM code validation:

Validation:

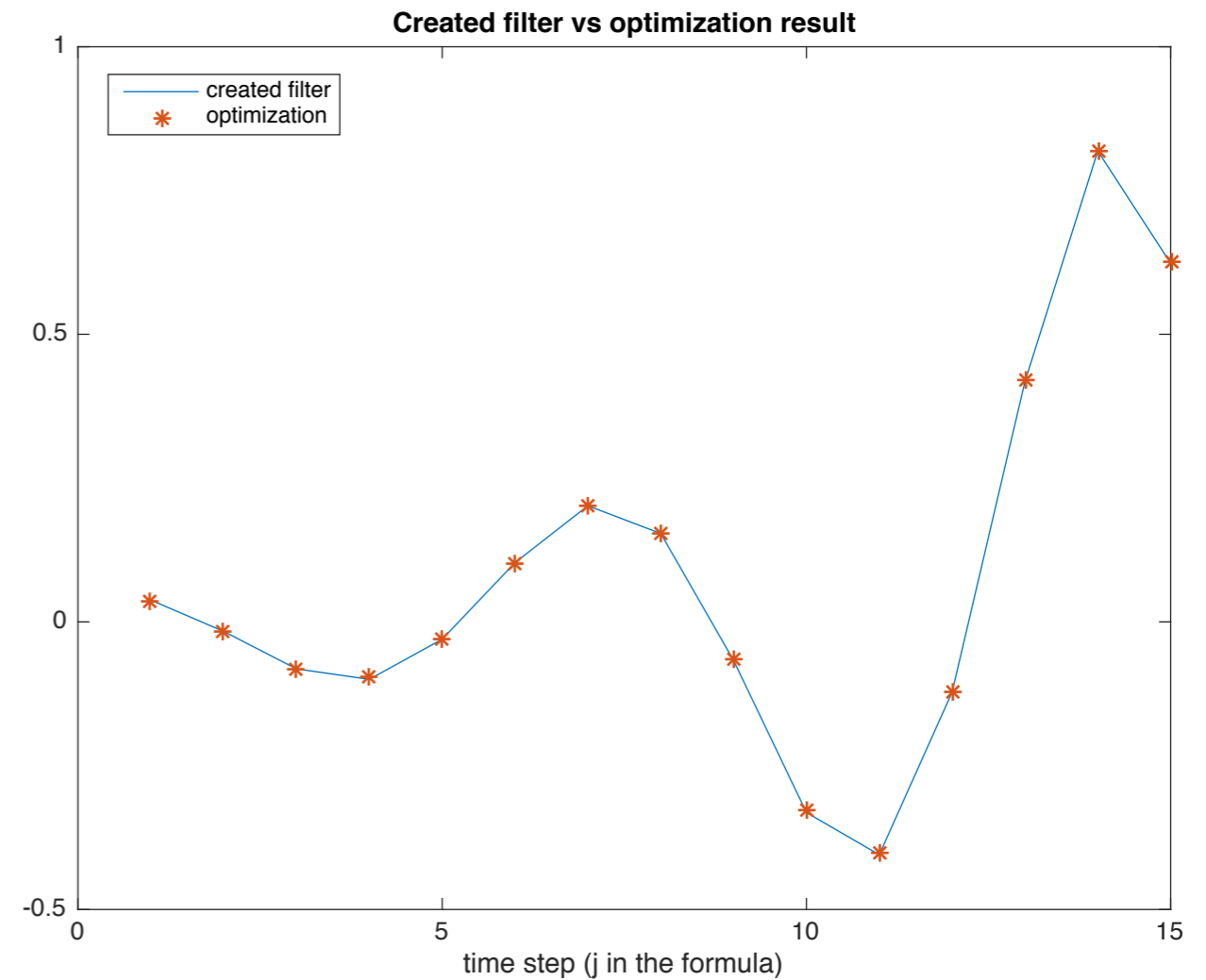
1. Generate stimulus
2. Chose a simple filter **k**
 $k_j = \exp((j - 15)/5)$
3. Use Poisson distribution for spike generation
4. Use generated stimulus and spikes in order to reconstruct the filter



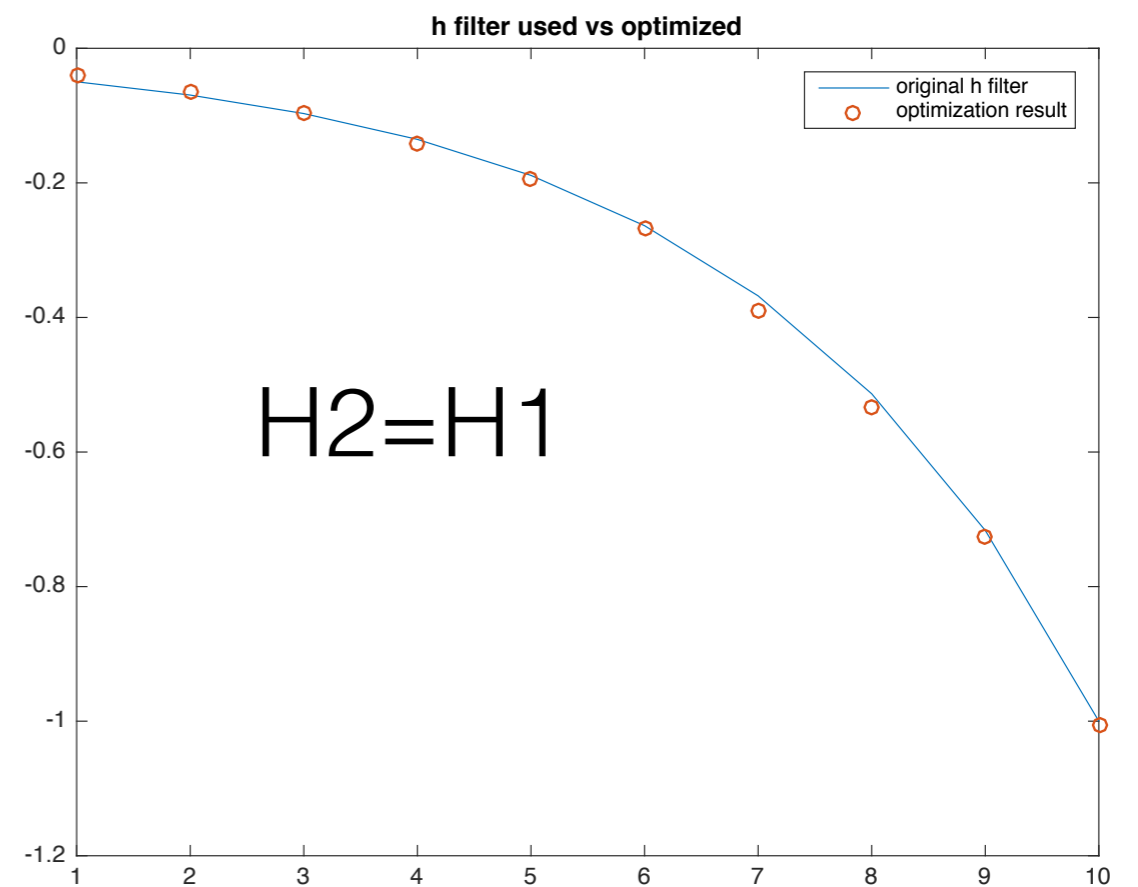
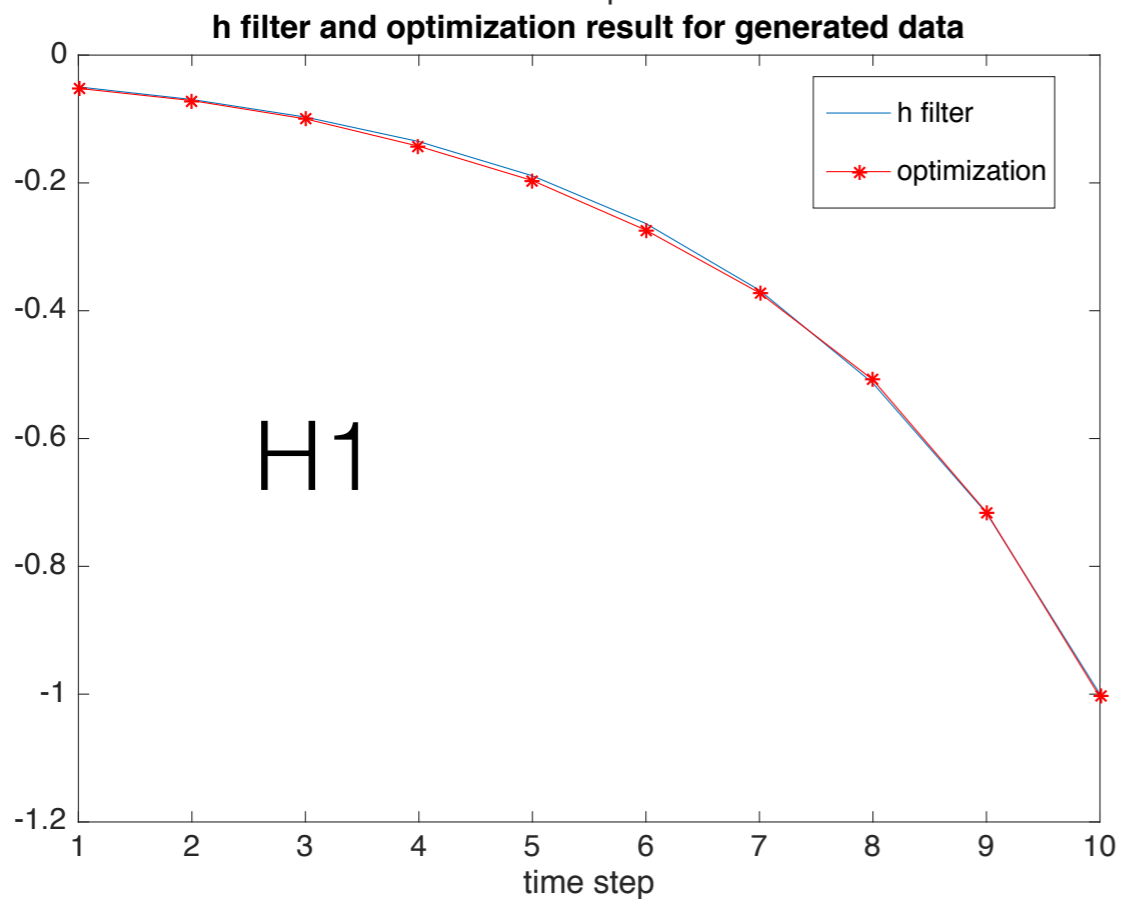
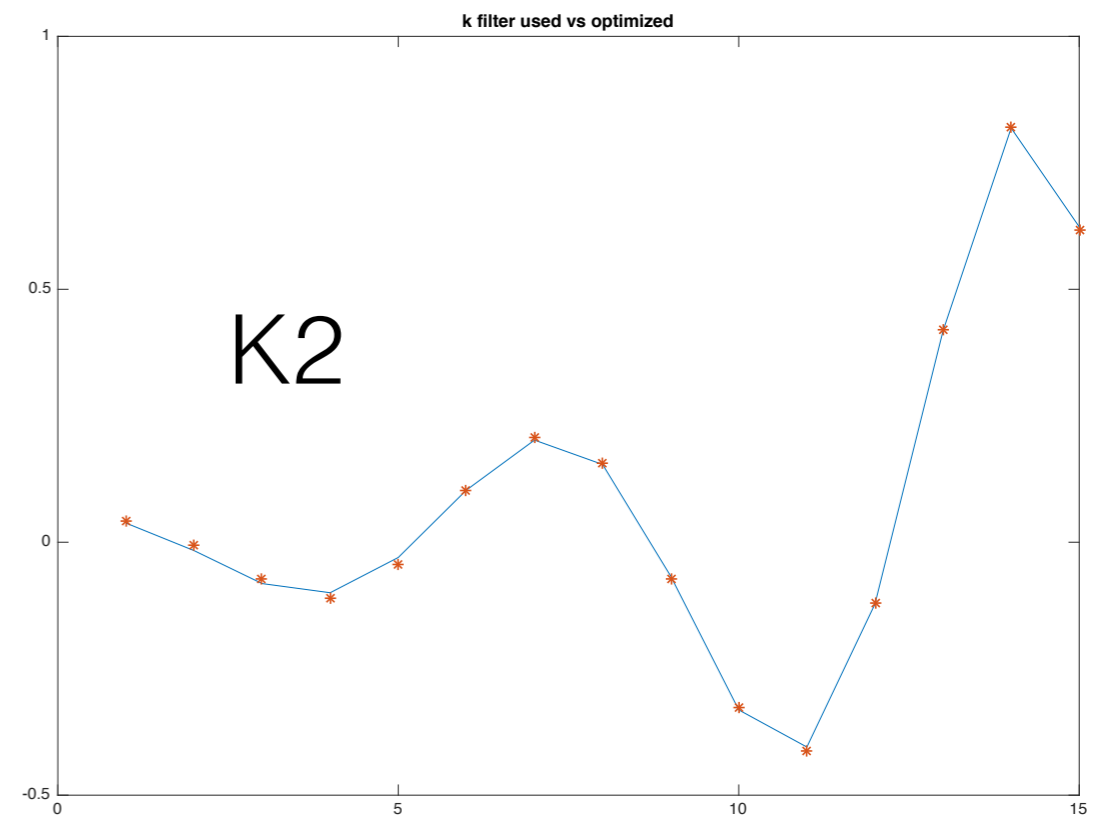
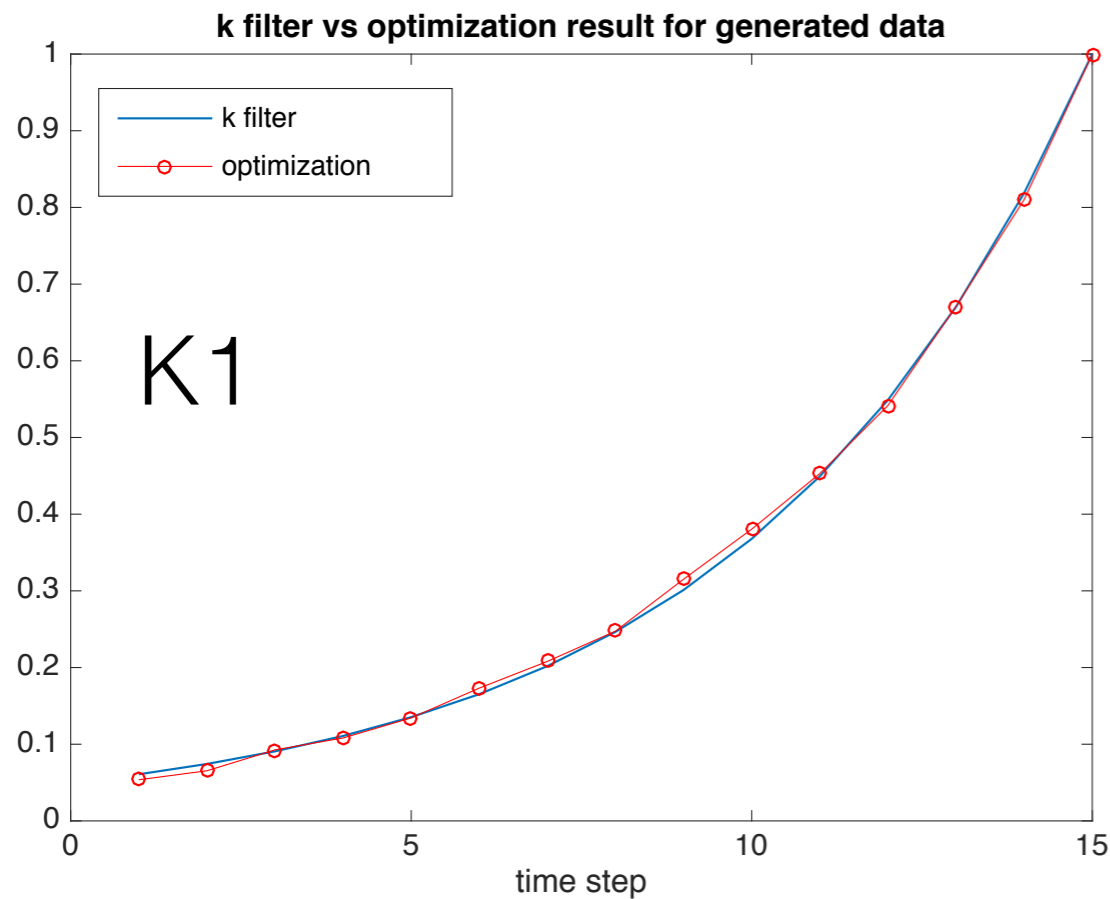
GLM code validation:

Try another test k-filter

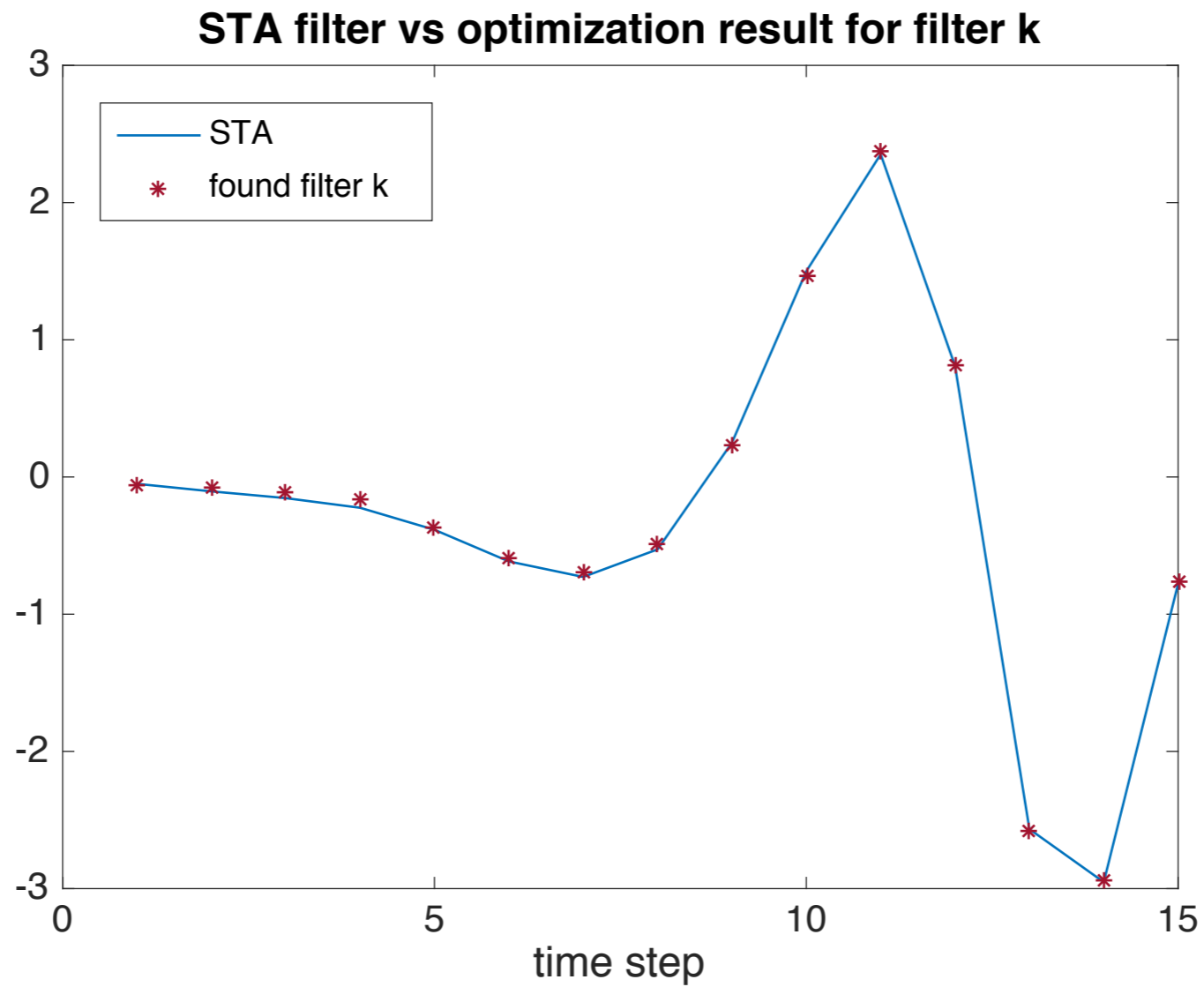
$$k_j = \exp((j - 15)/5) * \cos(2\pi j/7)$$



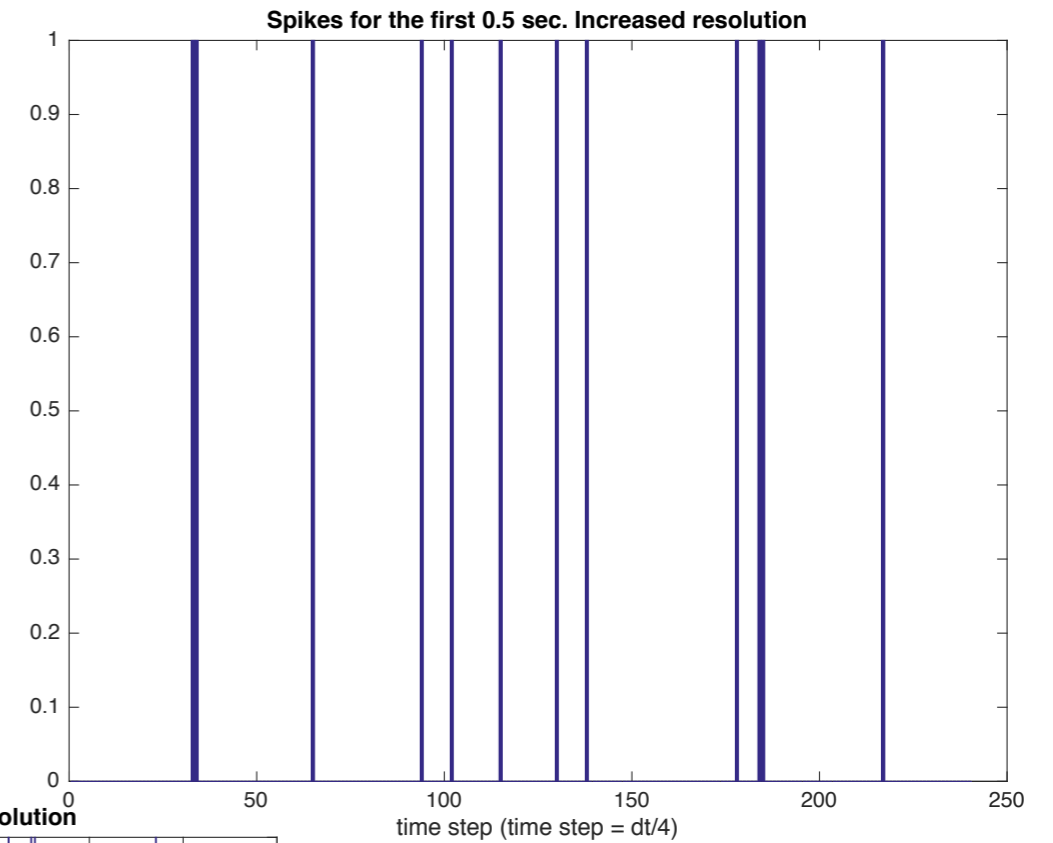
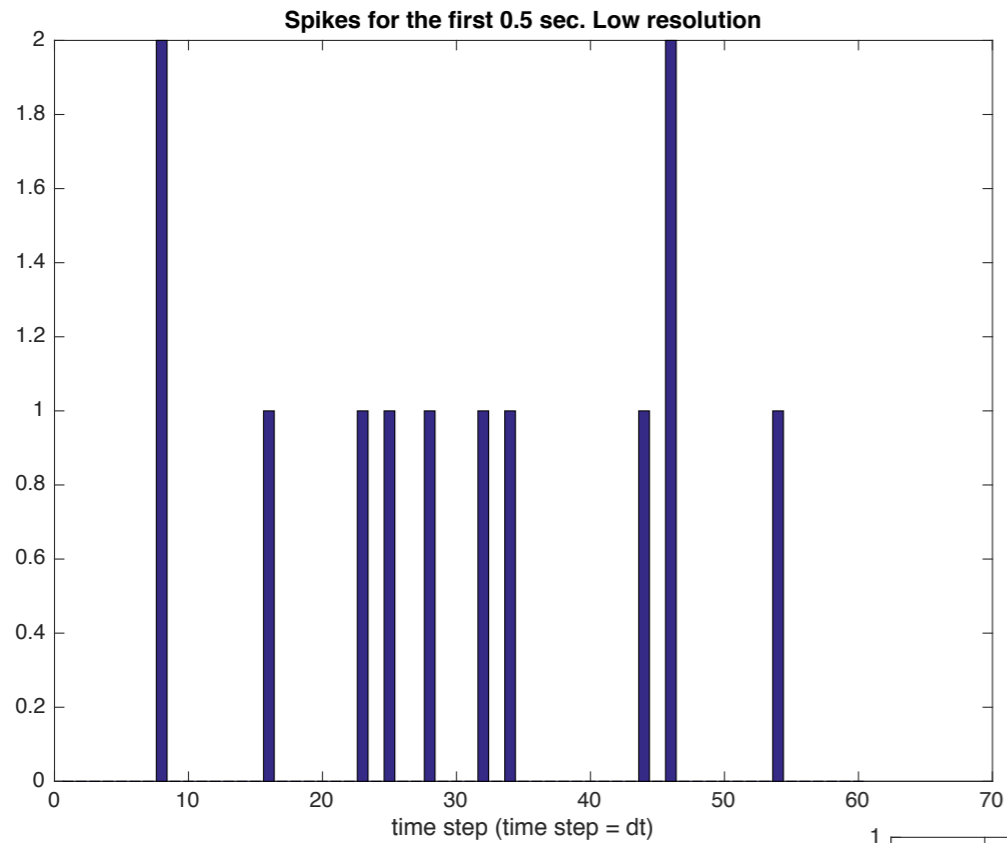
GLM code validation including history term



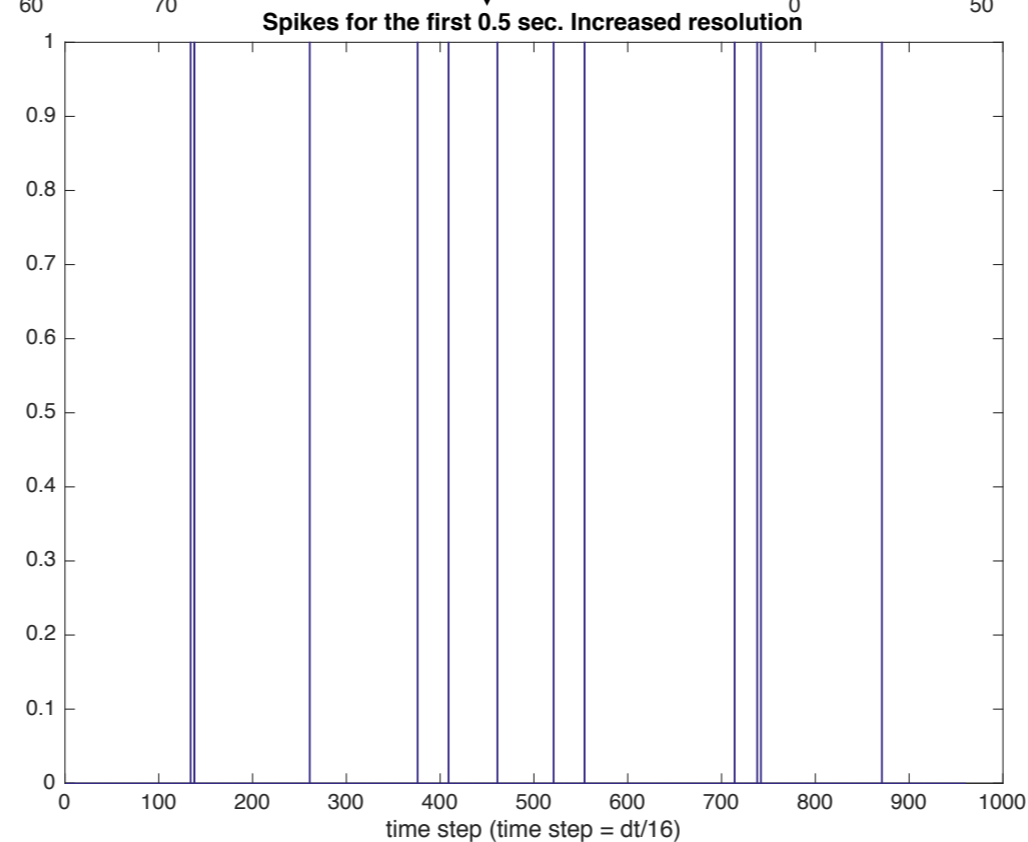
Optimal linear filter matches STA for RGC data:



Need higher time resolution to catch history term



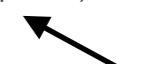
$dt/16$



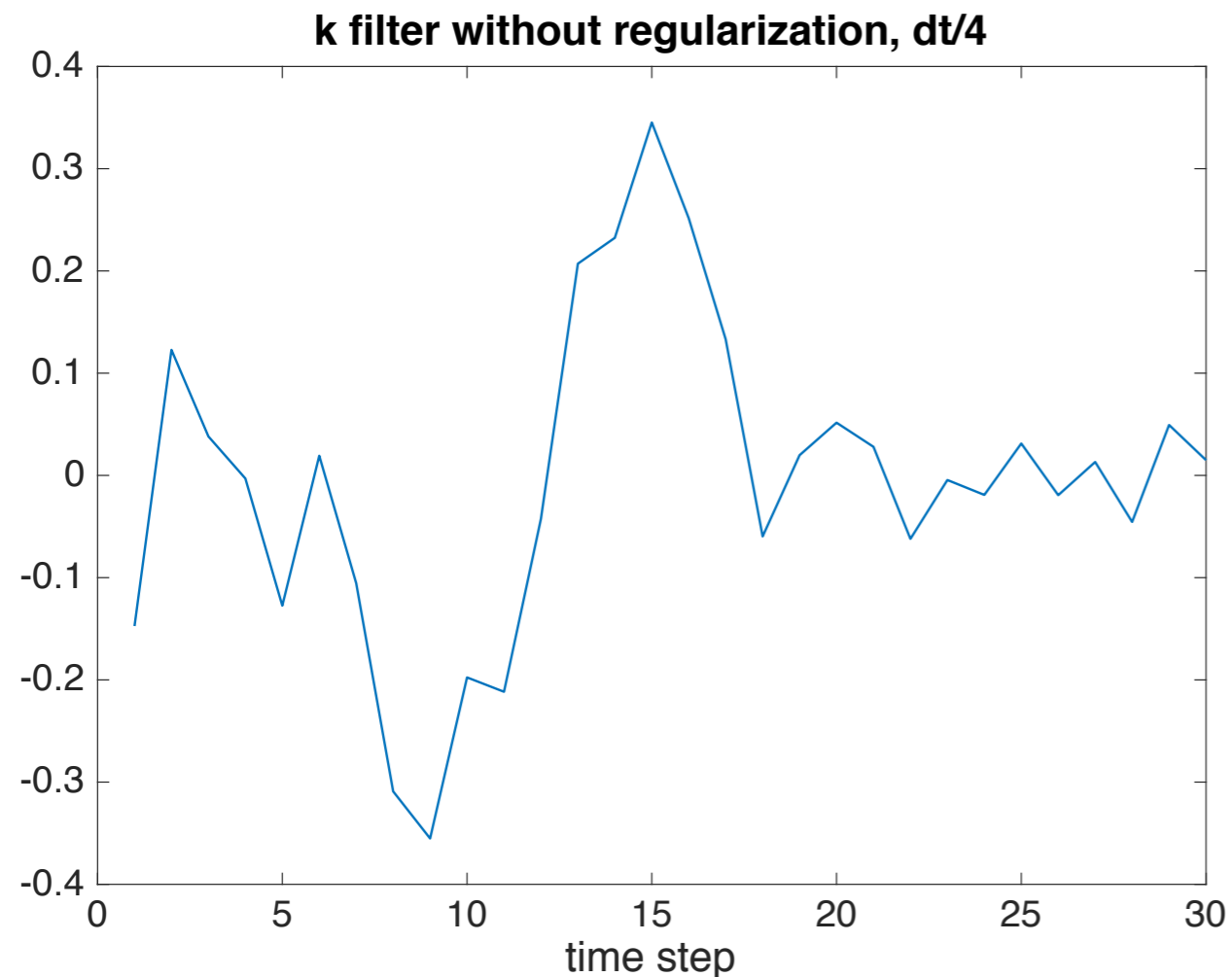
dt



$dt/4$



Regularization is needed at high resolutions



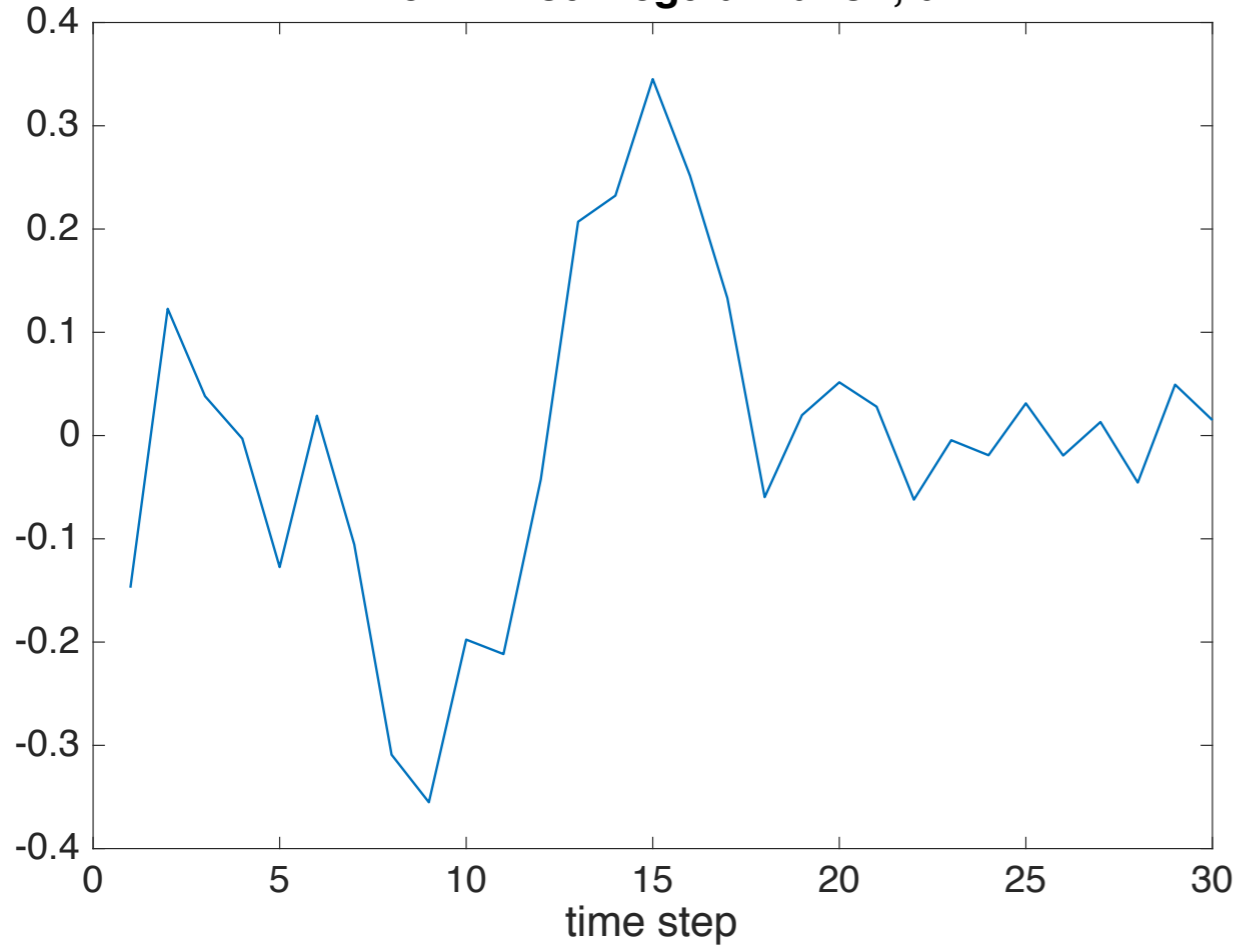
Solve regularized log-likelihood using gradient ascent method



$$RLL(\Theta) = \sum_t n(t)(\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b) - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}(t) + \mathbf{h} \cdot \mathbf{r}_{obs}(t) + b) - \lambda \sum_i (k_i - k_{i-1})^2$$

GLM implementation: increase the resolution.

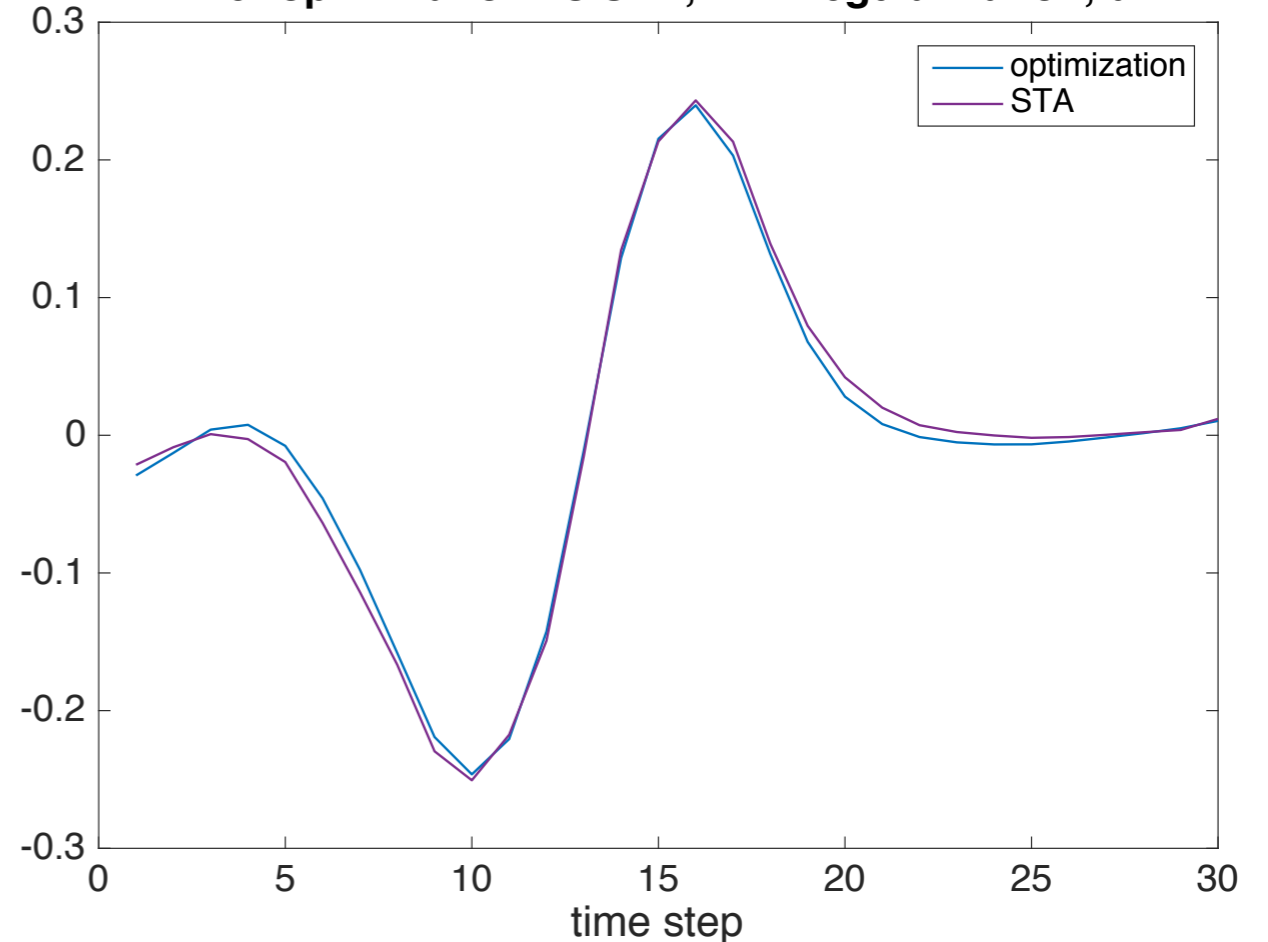
k filter without regularization, dt/4



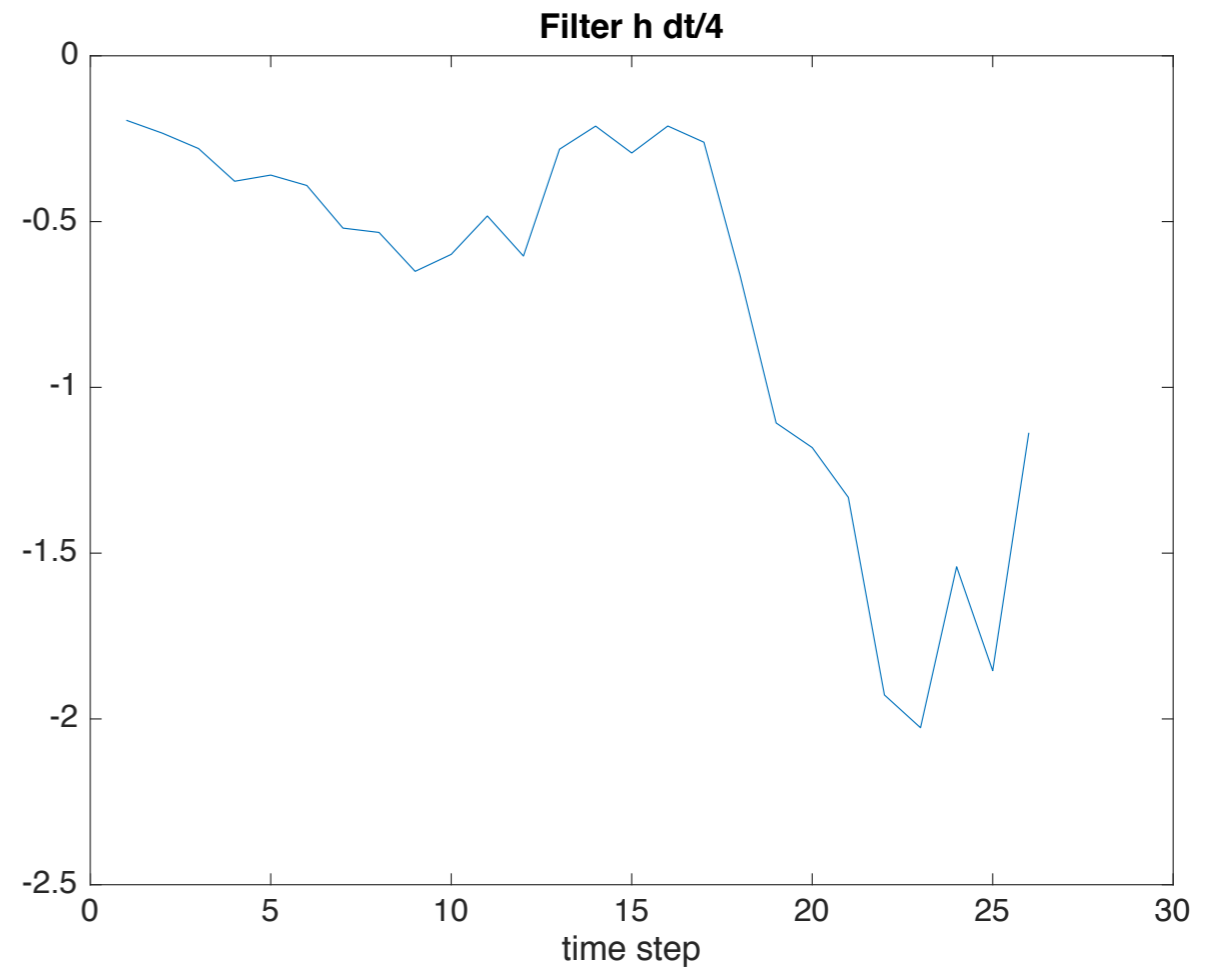
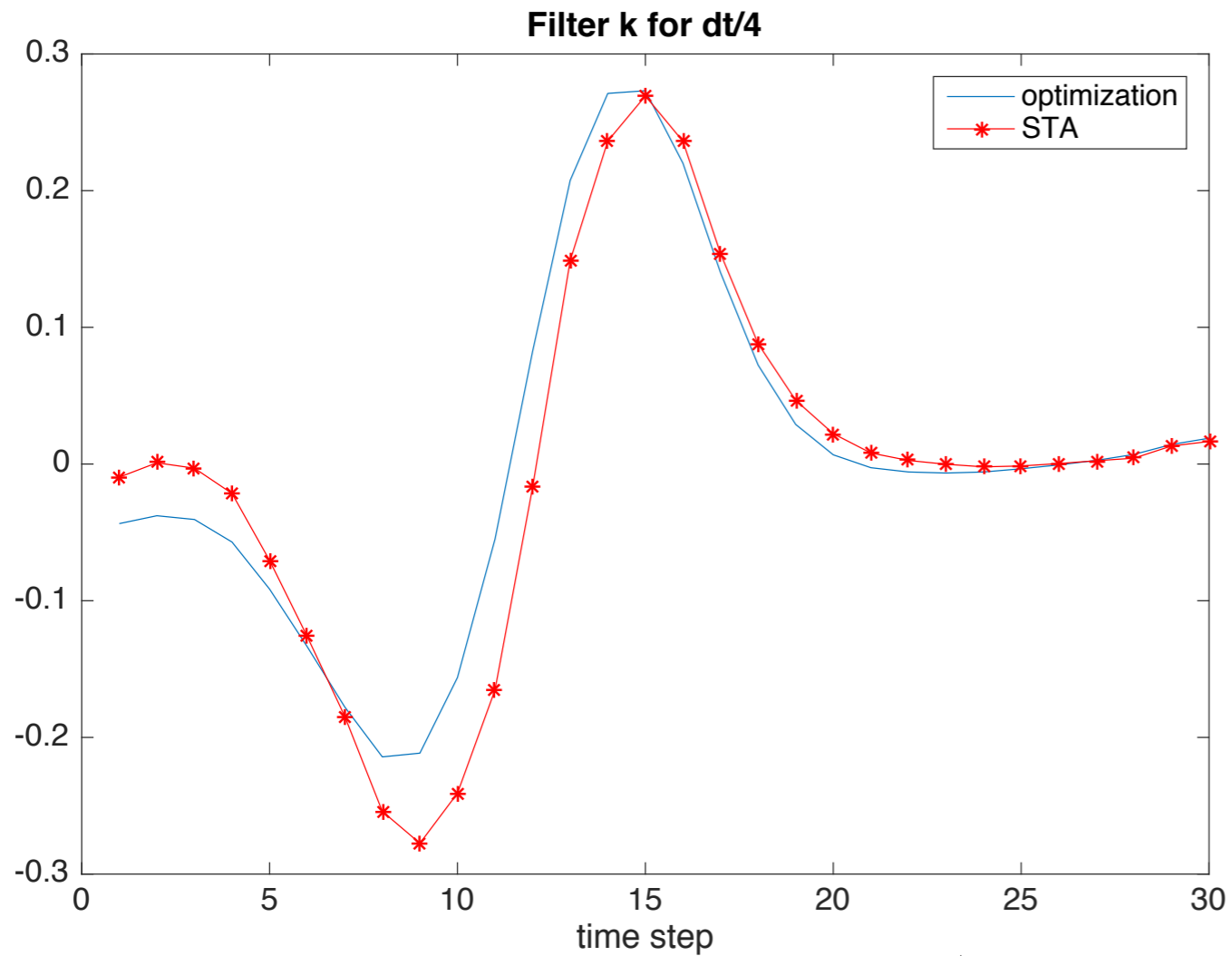
Resolution is dt/4, no history term.

LL $\sim 10^4$
Regularization term $\sim 10^2$
max difference between
STA and optimization
result is about 1%

K filter optimization vs STA, with regularization, dt/4



GLM with k,h and b parameters

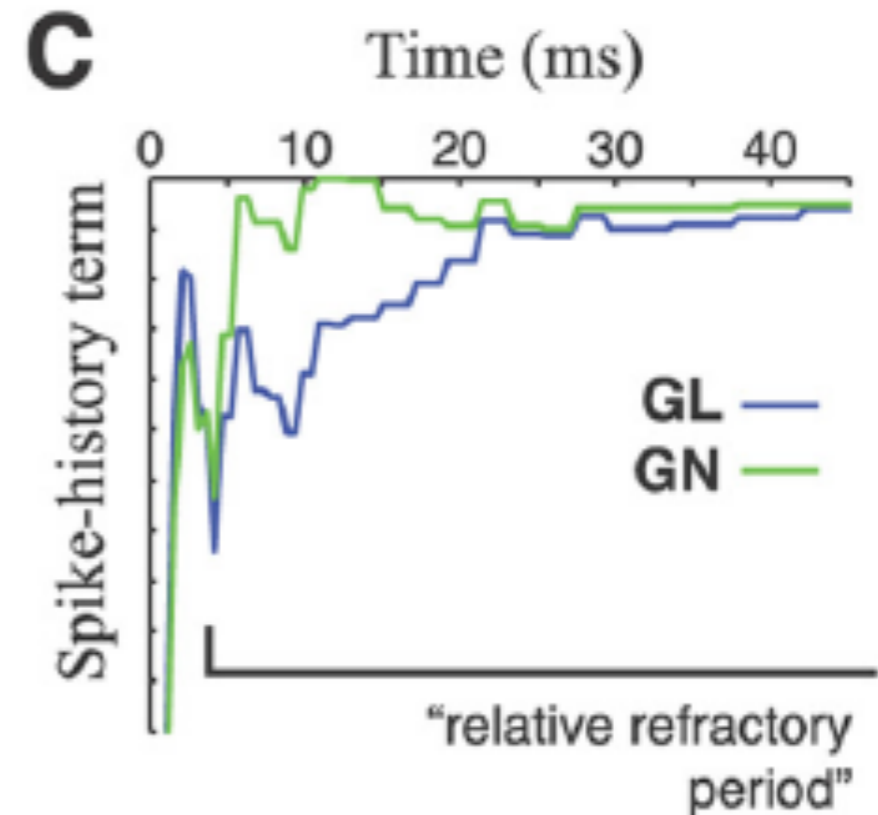
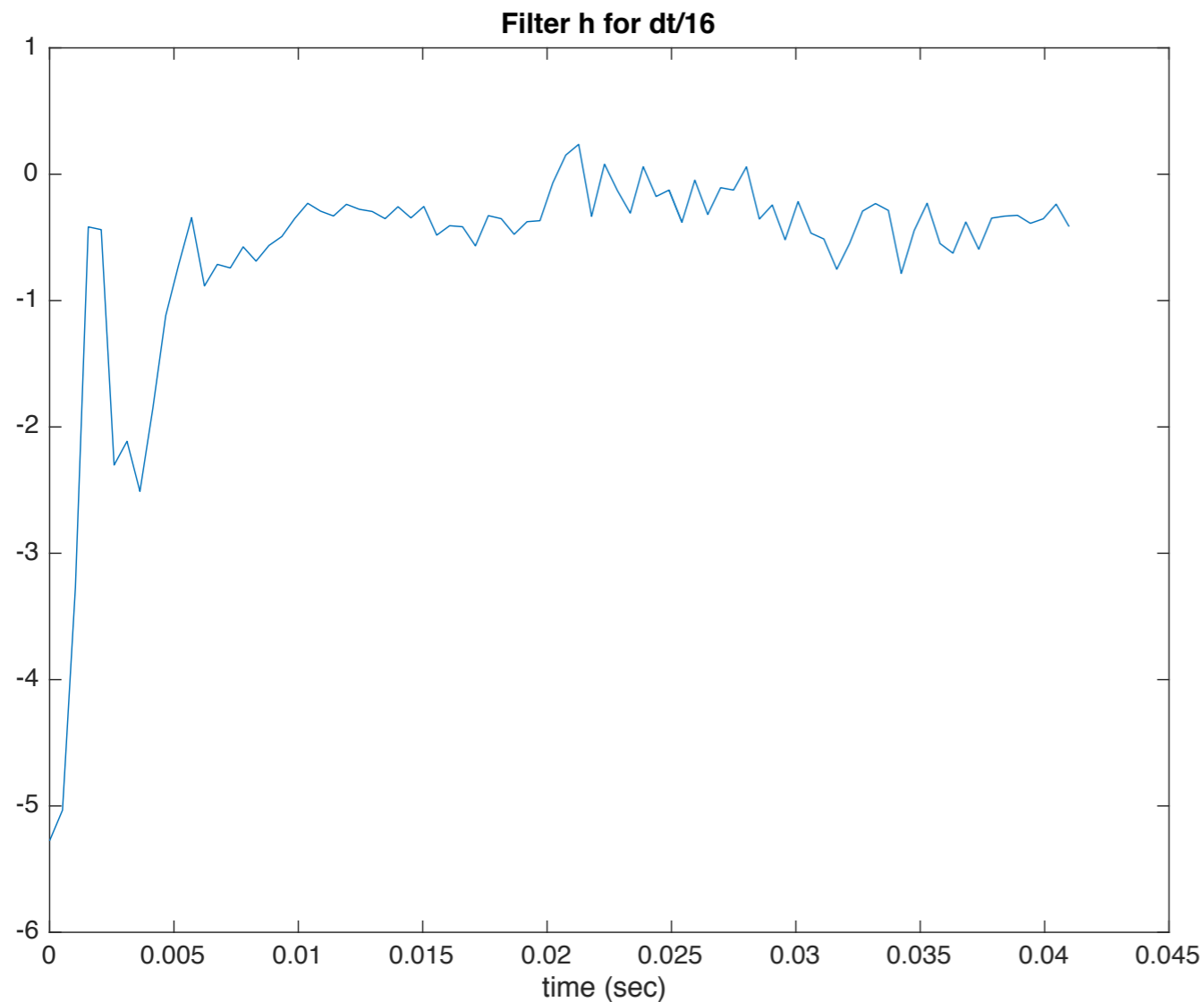


↑
OK

Resolution
dt/4

↖
Not OK

GLM with k,h and b parameters



neuron's history detected for resolution dt/16

Summary

- GLM algorithm was implemented and validated on generated data
- The history term was extracted using regularization of log-likelihood
- Optimization of up to 240 parameters simultaneously was implemented

Updated project schedule

October - ~~mid November~~ November

- ✓ Implement STA and STC models
- ✓ Test models on synthetic data set and validate models on real data set

~~November - December~~ December - mid February

- ✓ Implement Generalized Linear Model (GLM)
- ✓ Test model on synthetic data set and validate model on LGN data set

~~January - March~~ mid February - mid April

- Implement Generalized Quadratic Model (GQM) and Nonlinear Input Model (NIM)
- Test models on synthetic data set and validate models on LGN data set

~~April - May~~ Mid April - May

- Collect results and prepare final report

References

1. McFarland JM, Cui Y, Butts DA (2013) Inferring nonlinear neuronal computation based on physiologically plausible inputs. PLoS Computational Biology 9(7): e1003142.
2. Butts DA, Weng C, Jin JZ, Alonso JM, Paninski L (2011) Temporal precision in the visual pathway through the interplay of excitation and stimulus-driven suppression. J. Neurosci. 31: 11313-27.
3. Simoncelli EP, Pillow J, Paninski L, Schwartz O (2004) Characterization of neural responses with stochastic stimuli. In: The cognitive neurosciences (Gazzaniga M, ed), pp 327–338. Cambridge, MA: MIT.
4. Paninski, L., Pillow, J., and Lewi, J. (2006). Statistical models for neural encoding, decoding, and optimal stimulus design.
5. Shlens, J. (2008). Notes on Generalized Linear Models of Neurons.

Appendix: Gradient in GLM with k,h and b (including regularization term)

for $i = 2$ to $M-1$ (except the 1st and the last elements), where M is the number of stimuli = stimulus_length - P + 1

$$\frac{dLL}{dk_i} = \sum_t n_t s_{it} - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}_t + \mathbf{h} \cdot \mathbf{r}_{obs_t} + b) * s_{it} - 2 * \lambda(k_i - k_{i-1}) + 2 * \lambda(k_{i+1} - k_i)$$

$$\frac{dLL}{dk_1} = \sum_t n_t s_{1t} - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}_t + \mathbf{h} \cdot \mathbf{r}_{obs_t} + b) * s_{1t} + 2 * \lambda(k_2 - k_1)$$

$$\frac{dLL}{dk_M} = \sum_t n_t s_{Mt} - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}_t + \mathbf{h} \cdot \mathbf{r}_{obs_t} + b) * s_{Mt} - 2 * \lambda(k_M - k_{M-1})$$

$$\frac{dLL}{dh_i} = \sum_t n_t r_{obs_{it}} - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}_t + \mathbf{h} \cdot \mathbf{r}_{obs_t} + b) * r_{obs_{it}}$$

$$\frac{dLL}{db} = \sum_t n_t - \sum_t \exp(\mathbf{k} \cdot \mathbf{s}_t + \mathbf{h} \cdot \mathbf{r}_{obs_t} + b)$$